



# AT93C46D

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## Three-Wire Automotive Temperature Serial EEPROM 1-Kbit (128 x 8 or 64 x 16)

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### Features

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- Medium-Voltage and Standard-Voltage Operations:
  - $V_{CC} = 2.5V$  to  $5.5V$
- User-Selectable Internally Organized as 128 x 8 (1K) or 64 x 16 (1K)
- Automotive Temperature Range:  $-40^{\circ}C$  to  $+125^{\circ}C$
- Three-Wire Serial Interface
- 2 MHz Clock Rate (5V)
- Self-Timed Write Cycle within 10 ms Maximum
- Automotive AEC-Q100 Qualified
- High Reliability:
  - Endurance: 1,000,000 write cycles
  - Data retention: 100 years
- Green Package Options (Lead-free/Halide-free/RoHS compliant)

### Packages

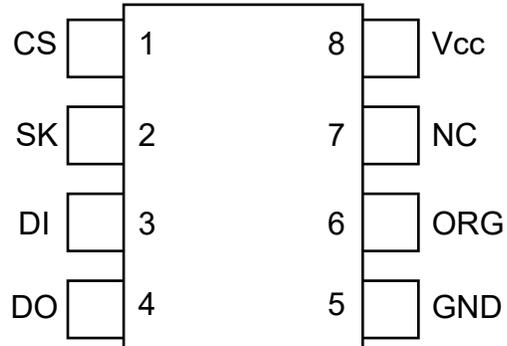
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- 8-Lead SOIC and 8-Lead TSSOP

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**1. Package Types (not to scale)****8-lead SOIC/TSSOP**  
(Top View)

## 2. Pin Descriptions

The descriptions of the pins are listed in [Table 2-1](#).

**Table 2-1. Pin Function Table**

Name	8-Lead SOIC	8-Lead TSSOP	Function
CS	1	1	Chip Select
SK	2	2	Serial Data Clock
DI	3	3	Serial Data Input
DO	4	4	Serial Data Output
GND	5	5	Ground
ORG	6	6	Internal Organization
NC	7	7	No Connect
VCC	8	8	Device Power Supply

### 2.1 Chip Select (CS)

The Chip Select (CS) pin is used to control device selection. The AT93C46D is selected when the CS pin is high. When the device is not selected, data will not be accepted via the Serial Data Input (DI) pin, and the Serial Output (DO) pin will remain in a high-impedance state.

### 2.2 Serial Data Clock (SK)

The Serial Data Clock (SK) pin is used to synchronize the communication between a master and the AT93C46D. Instructions, addresses or data present on the Serial Data Input (DI) pin is latched in on the rising edge of SK, while output on the Serial Data Output (DO) pin is also clocked out on the rising edge of SK.

### 2.3 Serial Data Input (DI)

The Serial Data Input (DI) pin is used to transfer data into the device. It receives instructions, addresses and data. Data is latched on the rising edge of the Serial Data Clock (SK).

### 2.4 Serial Data Output (DO)

The Serial Data Output (DO) pin is used to transfer data out of the AT93C46D. During a read sequence, data is shifted out on this pin after the rising edge of the Serial Data Clock (SK).

This pin also outputs the Ready/Busy status of the part if CS is brought high after being low for a minimum of  $t_{CS}$  and an erase or write operation has been initiated.

### 2.5 Ground (GND)

The ground reference for the power supply. The Ground (GND) pin should be connected to the system ground.

### 2.6 Internal Organization (ORG)

The Internal Organization (ORG) pin is used to select between the x16 or x8 memory organizations of the device. When the ORG pin is tied to V<sub>CC</sub>, the x16 memory organization is selected. When the ORG pin is tied to GND, the x8 memory organization is selected.

If the ORG pin is left unconnected and the application does not load the input beyond the capability of the internal 1 M $\Omega$  pull-up resistor, then the x16 organization is selected.

### 2.7 Device Power Supply ( $V_{CC}$ )

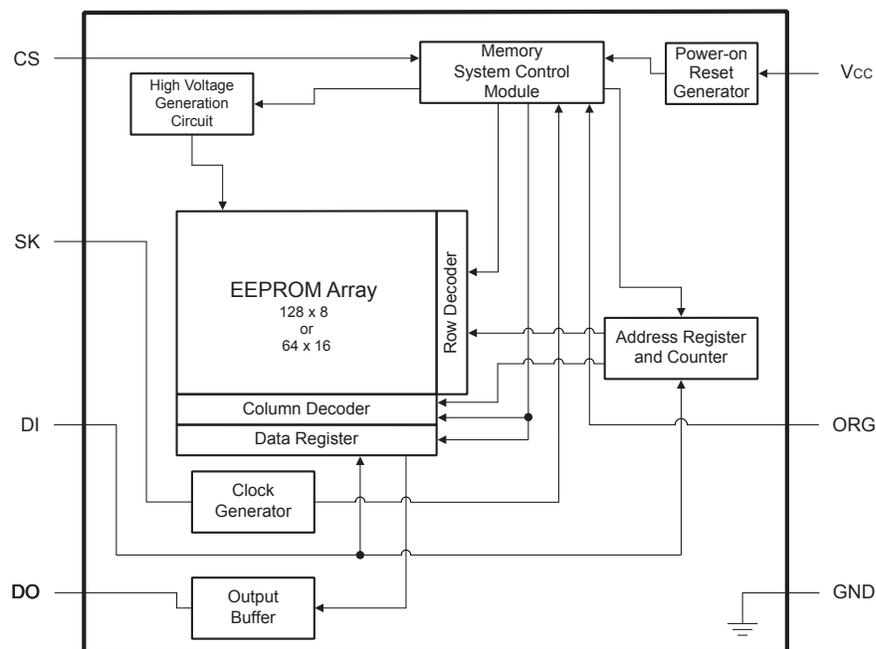
The Device Power Supply ( $V_{CC}$ ) pin is used to supply the source voltage to the device. Operations at invalid  $V_{CC}$  voltages may produce spurious results and should not be attempted.

### 3. Description

The AT93C46D provides 1,024 bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 64 words of 16 bits each (when the ORG pin is connected to  $V_{CC}$ ) and 128 words of 8 bits each (when the ORG pin is tied to GND). The device is optimized for use in many automotive applications where low-power and low-voltage operations are essential. The AT93C46D is available in space-saving 8-lead SOIC and 8-lead TSSOP packages. All packages operate from 2.5V to 5.5V.

The AT93C46D is enabled through the Chip Select (CS) pin and accessed via a three-wire serial interface consisting of Data Input (DI), Data Output (DO), and Serial Data Clock (SK). Upon receiving a `READ` instruction at DI, the address is decoded, and the data is clocked out serially on the DO pin. The write cycle is completely self-timed, and no separate erase cycle is required before write. The write cycle is only enabled when the part is in the Erase/Write Enable state. When CS is brought high following the initiation of a write cycle, the DO pin outputs the Ready/Busy status of the part.

#### 3.1 Block Diagram



## 4. Electrical Characteristics

### 4.1 Absolute Maximum Ratings

Temperature under bias	-55°C to +125°C
Storage temperature	-65°C to +150°C
V <sub>CC</sub>	6.25V
Voltage on any pin with respect to ground	-1.0V to +7.0V
DC output current	5.0 mA
ESD protection	2 kV

**Note:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### 4.2 DC and AC Operating Range

Table 4-1. DC and AC Operating Range

AT93C46D		
Operating Temperature (Case)	Automotive Temperature Range	-40°C to +125°C
V <sub>CC</sub> Power Supply	Low-Voltage Grade	2.5V to 5.5V

### 4.3 DC Characteristics

Table 4-2. DC Characteristics<sup>(1)</sup>

Parameter	Symbol	Minimum	Typical	Maximum	Units	Test Conditions
Supply Voltage	V <sub>CC1</sub>	2.5	—	5.5	V	
Supply Voltage	V <sub>CC2</sub>	4.5	—	5.5	V	
Supply Current	I <sub>CC1</sub>	—	0.5	2.0	mA	V <sub>CC</sub> = 5.0V, Read at 1 MHz
Supply Current	I <sub>CC2</sub>	—	0.5	2.0	mA	V <sub>CC</sub> = 5.0V, Write at 1 MHz
Standby Current (2.5V Option)	I <sub>SB2</sub>	—	6.0	10.0	μA	V <sub>CC</sub> = 2.5V, CS = 0V
Standby Current (5.0V Option)	I <sub>SB3</sub>	—	10.0	15.0	μA	V <sub>CC</sub> = 5.0V, CS = 0V
Input Leakage Current	I <sub>IL</sub>	—	0.1	1.0	μA	V <sub>IN</sub> = 0 to V <sub>CC</sub>
Output Leakage Current	I <sub>LO</sub>	—	0.1	1.0	μA	V <sub>OUT</sub> = 0 to V <sub>CC</sub>
Input Low-Voltage	V <sub>IL1</sub>	-0.6	—	0.8	V	2.5V ≤ V <sub>CC</sub> ≤ 5.5V (Note 2)
Input High-Voltage	V <sub>IH1</sub>	2.0	—	V <sub>CC</sub> + 1	V	2.5V ≤ V <sub>CC</sub> ≤ 5.5V (Note 2)

.....continued

Parameter	Symbol	Minimum	Typical	Maximum	Units	Test Conditions
Output Low-Voltage	VOL1	—	—	0.4	V	$2.5V \leq V_{CC} \leq 5.5V$ , $I_{OL} = 2.1 \text{ mA}$
Output High-Voltage	VOH1	2.4	—	—	V	$2.5V \leq V_{CC} \leq 5.5V$ , $I_{OH} = -0.4 \text{ mA}$

**Note:**

1. Applicable over recommended operating range from:  $T_A = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ ,  $V_{CC} = 2.5V$  to  $5.5V$  (unless otherwise noted).
2.  $V_{IL}$  min and  $V_{IH}$  max are reference only and are not tested.

## 4.4 AC Characteristics

Table 4-3. AC Characteristics<sup>(1)</sup>

Parameter	Symbol	Minimum	Typical	Maximum	Units	Test Conditions
Clock Frequency, SK	$f_{SK}$	0	—	2	MHz	$4.5V \leq V_{CC} \leq 5.5V$
		0	—	1	MHz	$2.5V \leq V_{CC} \leq 5.5V$
High Time, SK	$t_{SKH}$	250	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$
		250	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$
Low Time, SK	$t_{SKL}$	250	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$
		250	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$
Minimum CS Low Time	$t_{CS}$	250	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$
		250	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$
CS Setup Time	$t_{CSS}$	50	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
		50	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
DI Setup Time	$t_{DIS}$	100	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
		100	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
CS Hold Time	$t_{CSH}$	0	—	—	ns	Relative to SK
DI Hold Time	$t_{DIH}$	100	—	—	ns	$4.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
		100	—	—	ns	$2.5V \leq V_{CC} \leq 5.5V$ , Relative to SK
Output Delay to 1	$t_{PD1}$	—	—	250	ns	$4.5V \leq V_{CC} \leq 5.5V$
		—	—	500	ns	$2.5V \leq V_{CC} \leq 5.5V$
Output Delay to 0	$t_{PD0}$	—	—	250	ns	$4.5V \leq V_{CC} \leq 5.5V$
		—	—	500	ns	$2.5V \leq V_{CC} \leq 5.5V$
CS to Status Valid	$t_{SV}$	—	—	250	ns	$4.5V \leq V_{CC} \leq 5.5V$
		—	—	250	ns	$2.5V \leq V_{CC} \leq 5.5V$

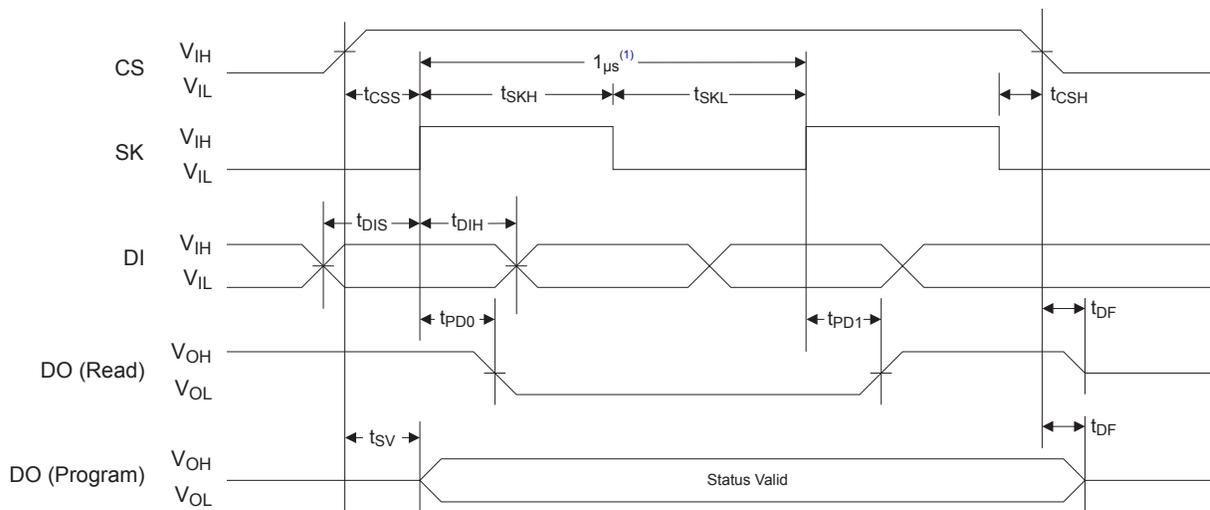
.....continued						
Parameter	Symbol	Minimum	Typical	Maximum	Units	Test Conditions
CS to DO in High-impedance	$t_{DF}$	—	—	100	ns	$4.5V \leq V_{CC} \leq 5.5V$ , CS = $V_{IL}$
		—	—	150	ns	$2.5V \leq V_{CC} \leq 5.5V$ , CS = $V_{IL}$
Write Cycle Time	$t_{WP}$	0.1	3	10	ms	$1.8V \leq V_{CC} \leq 5.5V$

**Note:**

- Applicable over recommended operating range from  $T_A = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ ,  $V_{CC} = \text{As Specified}$ ,  $C_L = 1 \text{ TTL Gate}$  and  $100 \text{ pF}$  (unless otherwise noted).

## 4.5 Synchronous Data Timing

Figure 4-1. Synchronous Data Timing



**Note:**

- This is the minimum SK period.

## 4.6 Electrical Specifications

### 4.6.1 Power-Up Requirements and Reset Behavior

During a power-up sequence, the  $V_{CC}$  supplied to the AT93C46D should monotonically rise from GND to the minimum  $V_{CC}$  level, as specified in Table 4-1, with a slew rate no faster than  $0.1 \text{ V}/\mu\text{s}$ .

#### 4.6.1.1 Device Reset

To prevent inadvertent write operations or any other spurious events from occurring during a power-up sequence, the AT93C46D includes a Power-on Reset (POR) circuit. Upon power-up, the device will not respond to any commands until the  $V_{CC}$  level crosses the internal voltage threshold ( $V_{POR}$ ) that brings the device out of Reset and into Standby mode.

The system designer must ensure the instructions are not sent to the device until the  $V_{CC}$  supply has reached a stable value greater than or equal to the minimum  $V_{CC}$  level. Additionally, once the  $V_{CC}$  is greater than or equal to the minimum  $V_{CC}$  level, the bus master must wait at least  $t_{PUP}$  before sending the first command to the device. See Power-up Conditions<sup>(1)</sup> for the values associated with these power-up parameters.

**Table 4-4. Power-up Conditions<sup>(1)</sup>**

Symbol	Parameter	Min.	Max.	Units
$t_{PUP}$	Time required after $V_{CC}$ is stable before the device can accept commands	100	—	$\mu$ s
$V_{POR}$	Power-on Reset Threshold Voltage	—	1.5	V
$t_{POFF}$	Minimum time at $V_{CC} = 0V$ between power cycles	500	—	ms

**Note:**

1. These parameters are characterized but they are not 100% tested in production.

If an event occurs in the system where the  $V_{CC}$  level supplied to the AT93C46D drops below the maximum  $V_{POR}$  level specified, it is recommended that a full power cycle sequence be performed by first driving the  $V_{CC}$  pin to GND, waiting at least the minimum  $t_{POFF}$  time and then performing a new power-up sequence in compliance with the requirements defined in this section.

### 4.6.2 Pin Capacitance

**Table 4-5. Pin Capacitance<sup>(1)</sup>**

Symbol	Test Condition	Max.	Units	Conditions
$C_{OUT}$	Output Capacitance (DO)	5	pF	$V_{OUT} = 0V$ , $T_A = 25^\circ C$ , $F = 1.0$ MHz, $V_{CC} = +5V$
$C_{IN}$	Input Capacitance (CS, SK, DI, ORG)	5	pF	$V_{IN} = 0V$ , $T_A = 25^\circ C$ , $F = 1.0$ MHz, $V_{CC} = +5V$

**Note:**

1. This parameter is characterized but is not 100% tested in production.

### 4.6.3 EEPROM Cell Performance Characteristics

**Table 4-6. EEPROM Cell Performance Characteristics**

Operation	Test Condition	Min.	Max.	Units
Write Endurance <sup>(1)</sup>	$T_A = 25^\circ C$ , $V_{CC} = 5.0V$	1,000,000	—	Write Cycles
Data Retention <sup>(1)</sup>	$T_A = 55^\circ C$	100	—	Years

**Note:**

1. Performance is determined through characterization and the qualification process.

## 5. Device Commands and Addressing

The AT93C46D is accessed via a simple and versatile three-wire serial communication interface. Device operation is controlled by seven instructions issued by the Host processor. A valid instruction starts with a rising edge of CS and consists of a Start bit (SB), followed by the appropriate opcode, and the desired memory address location.

**Table 5-1. AT93C46D Instruction Set**

Instruction	SB	Opcode	Address		Data		Comments
			X8 <sup>(1)</sup>	X16 <sup>(1)</sup>	X8	X16	
READ	1	10	A <sub>6</sub> -A <sub>0</sub>	A <sub>5</sub> -A <sub>0</sub>			Reads data stored in memory at specified address.
EWEN	1	00	11XXXXX	11XXXX			Write Enable must precede all programming modes.
ERASE	1	11	A <sub>6</sub> -A <sub>0</sub>	A <sub>5</sub> -A <sub>0</sub>			Erases memory location A <sub>N</sub> -A <sub>0</sub> .
WRITE	1	01	A <sub>6</sub> -A <sub>0</sub>	A <sub>5</sub> -A <sub>0</sub>	D <sub>7</sub> -D <sub>0</sub>	D <sub>15</sub> -D <sub>0</sub>	Writes memory location A <sub>N</sub> -A <sub>0</sub> .
ERAL	1	00	10XXXXX	10XXXX			Erases all memory locations. Valid only at VCC2. See <a href="#">Table 4-2</a> .
WRAL	1	00	01XXXXX	01XXXX	D <sub>7</sub> -D <sub>0</sub>	D <sub>15</sub> -D <sub>0</sub>	Writes all memory locations. Valid only at VCC2. See <a href="#">Table 4-2</a> .
EWDS	1	00	00XXXXX	00XXXX			Disables all programming instructions.

**Note:**

- The 'X' in the address field represents a "don't care" bit, and must be sent to the device.

**Table 5-2. Organization Key for Timing Diagrams**

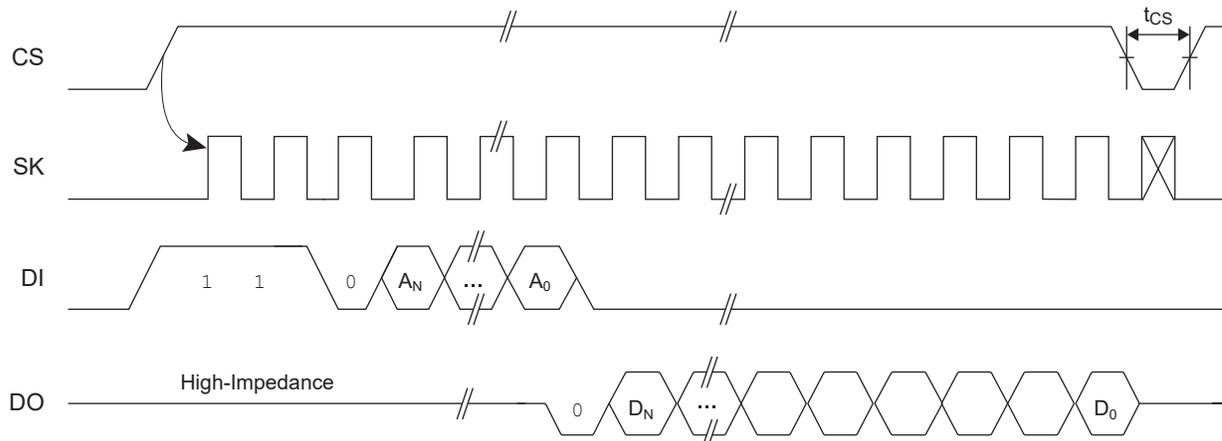
I/O	AT93C46D (1K)	
	x8	x16
A <sub>N</sub>	A <sub>6</sub>	A <sub>5</sub>
D <sub>N</sub>	D <sub>7</sub>	D <sub>15</sub>

### 5.1 Read Operation (READ)

The READ instruction contains the address code for the memory location to be read. After the instruction and address are decoded, data from the selected memory location is available at the DO pin. Output data changes are synchronized with the rising edges of the SK pin.

**Note:** A dummy bit (logic '0') precedes the 8-bit or 16-bit data output string.

Figure 5-1. READ Timing

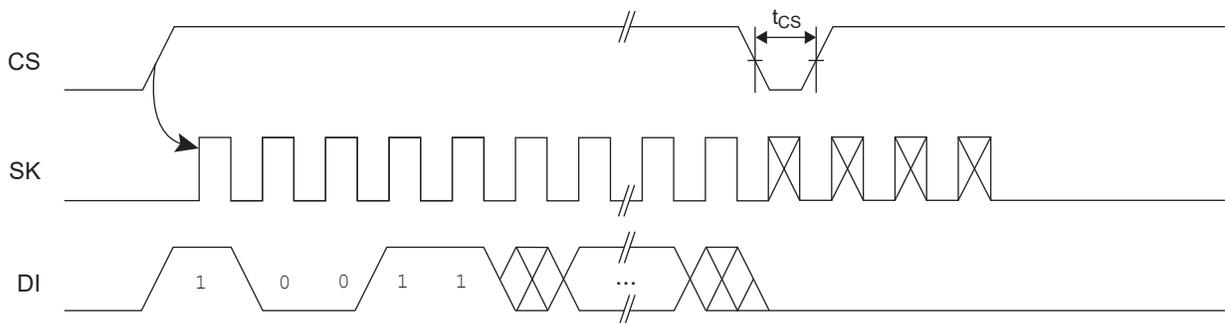


### 5.2 Erase/Write Enable (EWEN)

To ensure data integrity, the part automatically goes into the Erase/Write Disable (EWDS) state when power is first applied. An Erase/Write Enable (EWEN) instruction must be executed first before any programming instructions can be carried out.

**Note:** Once in the write enabled state, programming remains enabled until an EWDS instruction is executed, or V<sub>CC</sub> power is removed from the part.

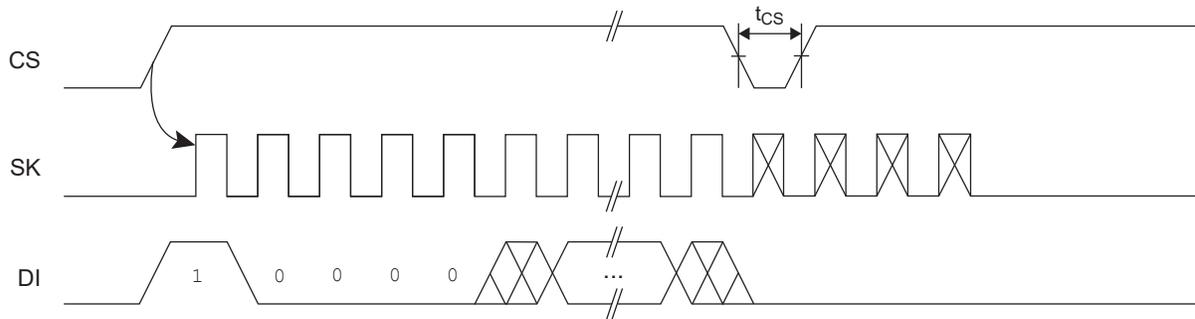
Figure 5-2. EWEN Timing



### 5.3 Erase/Write Disable (EWDS)

To protect against accidental data disturbance, the Erase/Write Disable (EWDS) instruction disables all programming modes and should be executed after all programming operations. The operation of the READ instruction is independent of both the EWEN and EWDS instructions and can be executed at any time.

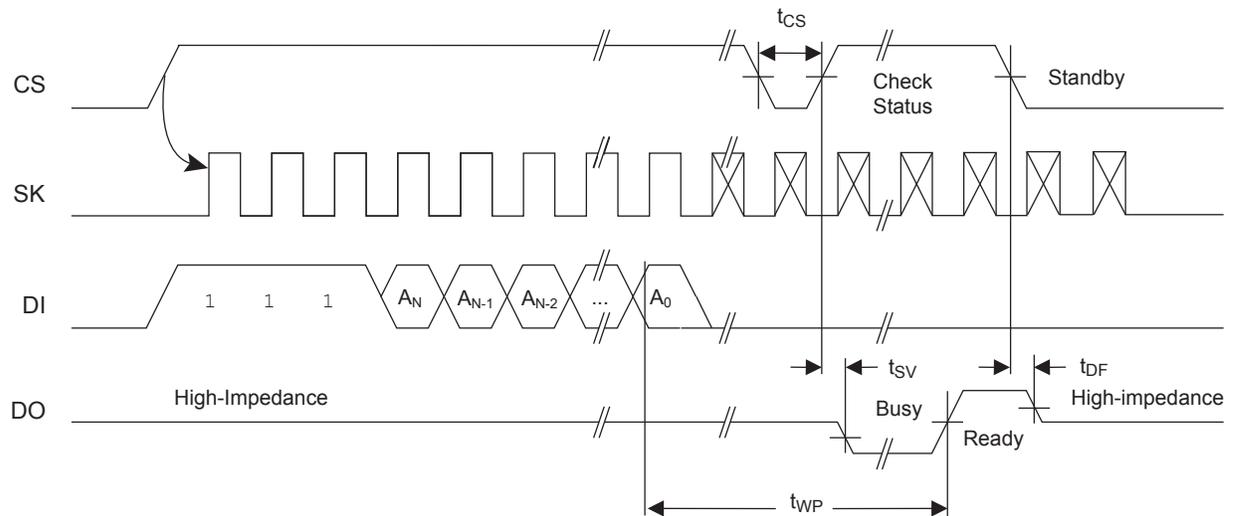
Figure 5-3. EWDS Timing



### 5.4 Erase Operation (ERASE)

The `ERASE` instruction programs all bits in the specified memory location to the logic '1' state. The self-timed erase cycle starts once the `ERASE` instruction and address are decoded. The DO pin outputs the Ready/Busy status of the part if CS is brought high after being kept low for a minimum of  $t_{CS}$ . A logic '1' at the DO pin indicates that the selected memory location has been erased, and the part is ready for another instruction.

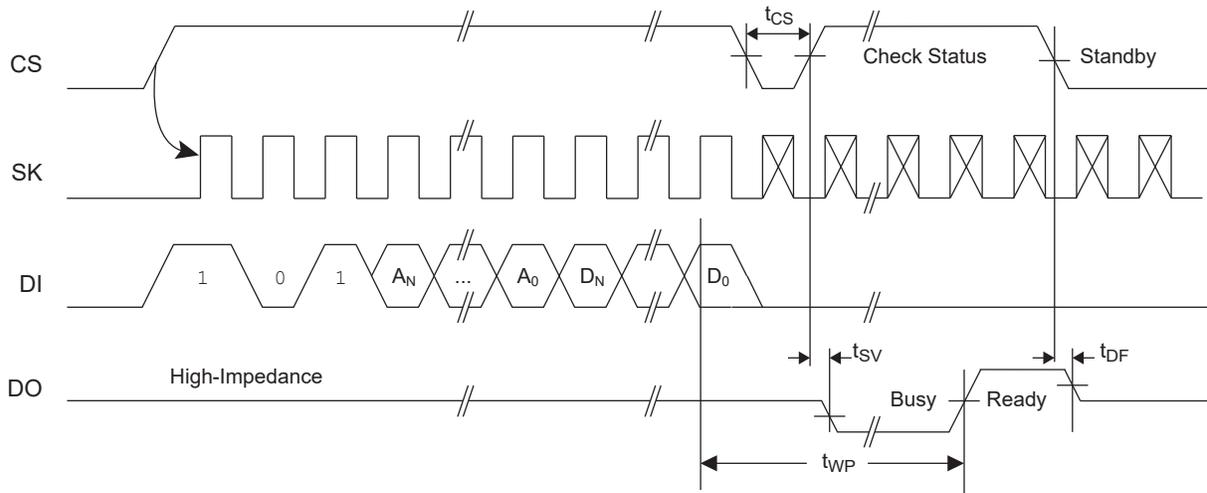
Figure 5-4. ERASE Timing



### 5.5 Write Operation (WRITE)

The `WRITE` instruction contains the 8 bits or 16 bits of data to be written into the specified memory location. The self-timed programming cycle,  $t_{WP}$ , starts after the last bit of data is received at DI pin. The DO pin outputs the Ready/Busy status of the part if CS is brought high after being kept low for a minimum of  $t_{CS}$ . A logic '0' at DO indicates that programming is still in progress. A logic '1' indicates that the memory location at the specified address has been written with the data pattern contained in the instruction, and the part is ready for further instructions. A Ready/Busy status cannot be obtained if CS is brought high after the end of the self-timed programming cycle,  $t_{WP}$ .

Figure 5-5. WRITE Timing

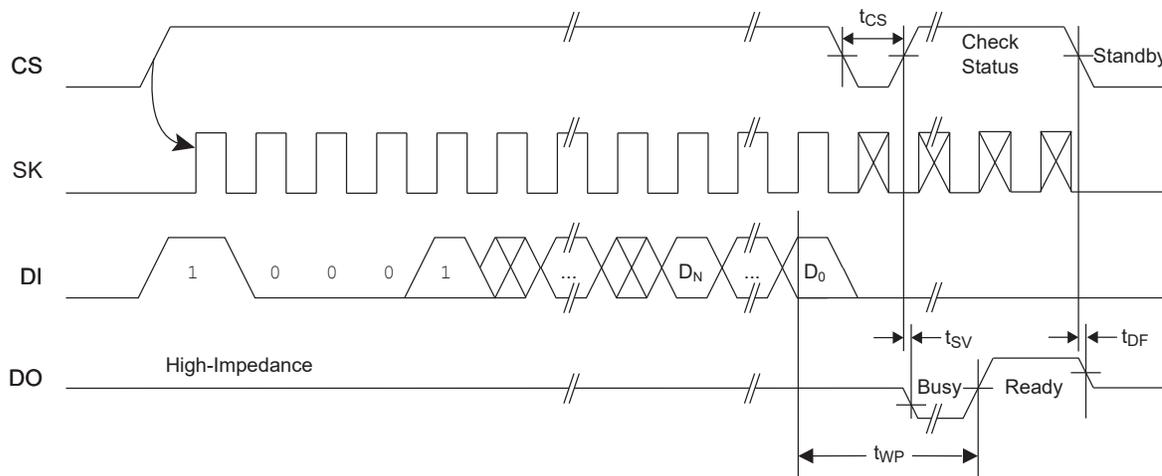


### 5.6 Write All (WRAL)

The Write All ( $WRAL$ ) instruction programs all memory locations with the data patterns specified in the instruction. The DO pin outputs the Ready/Busy status of the part if CS is brought high after being kept low for a minimum of  $t_{CS}$ .

**Note:** The  $WRAL$  instruction is valid only at  $V_{CC2}$  (see Table 4-2).

Figure 5-6. WRAL Timing

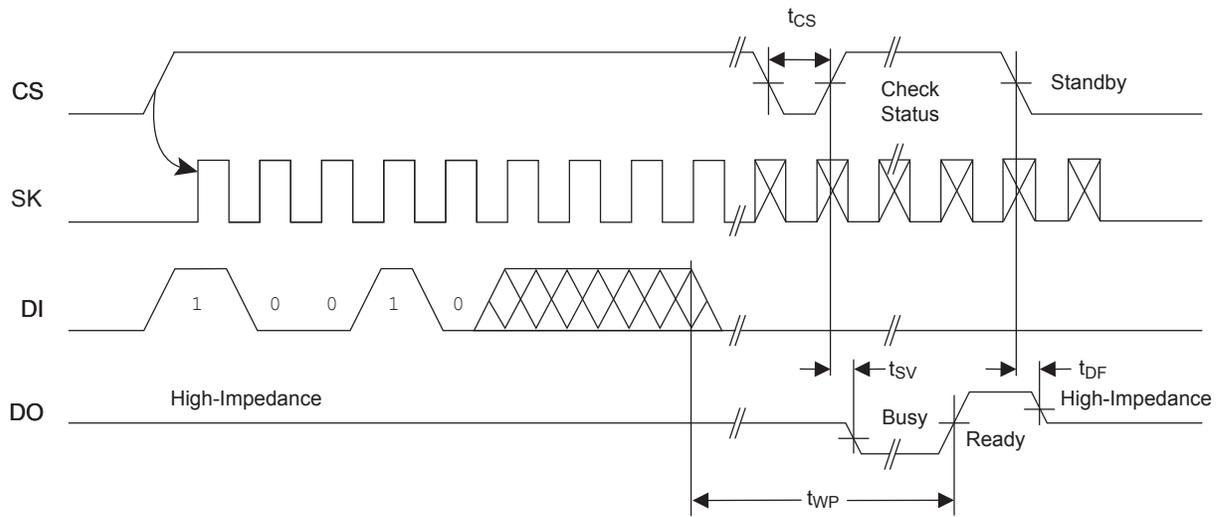


### 5.7 Erase All (ERAL)

The Erase All ( $ERAL$ ) instruction programs every bit in the memory array to the logic '1' state and is primarily used for testing purposes. The DO pin outputs the Ready/Busy status of the part if CS is brought high after being kept low for a minimum of  $t_{CS}$ .

**Note:** The  $ERAL$  instruction is valid only at  $V_{CC2}$  (see Table 4-2).

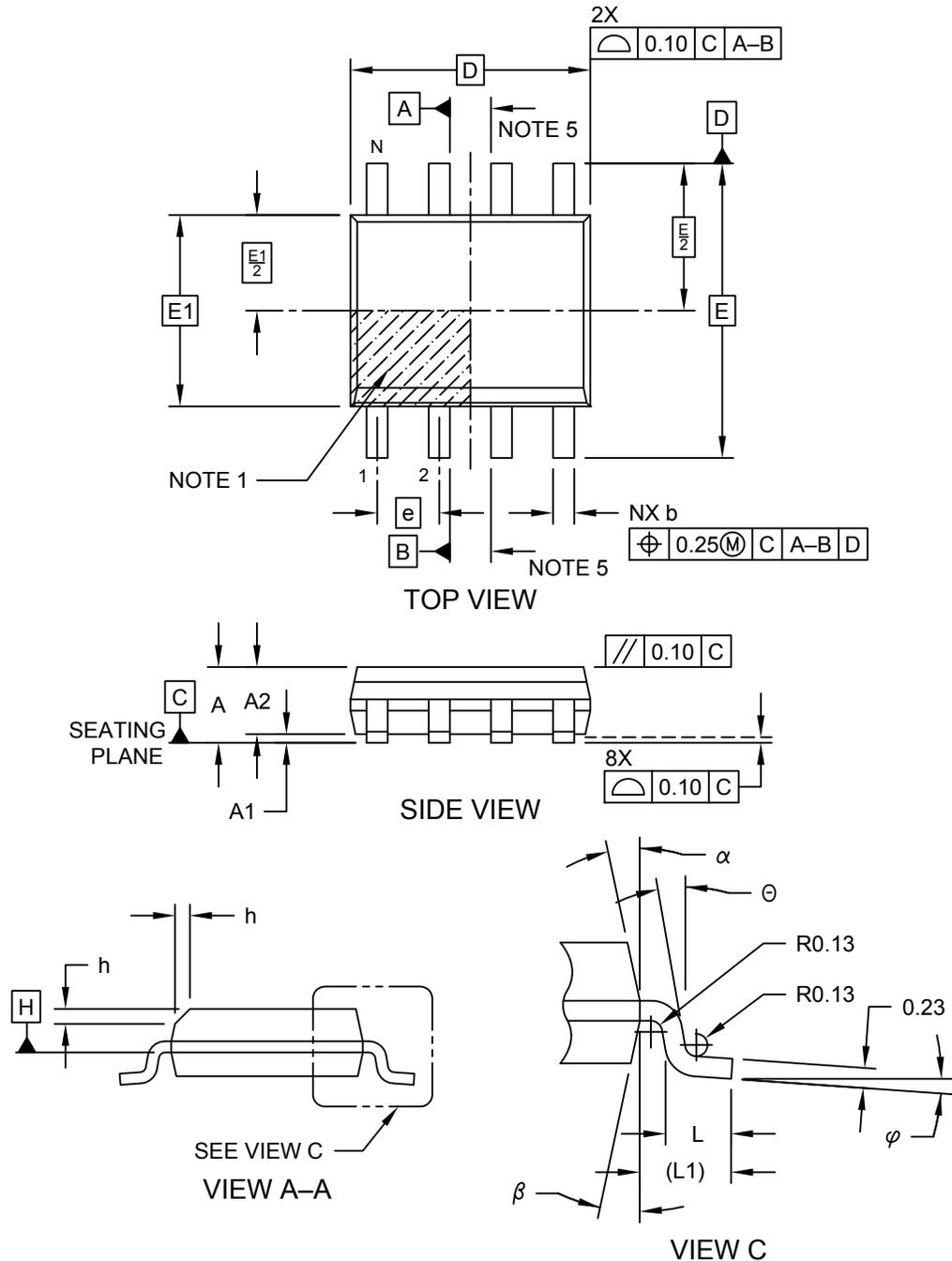
**Figure 5-7. ERAL Timing**





**8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 In.) Body [SOIC]**

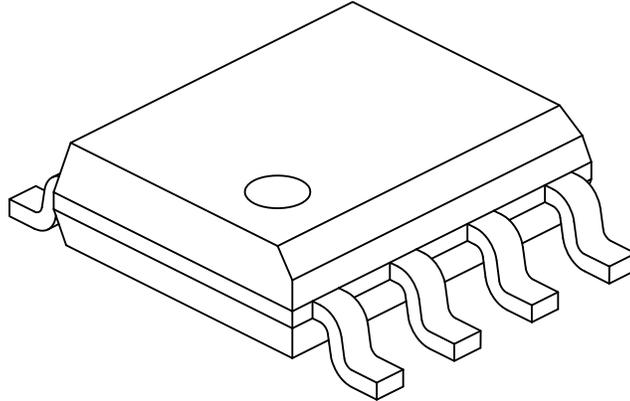
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing No. C04-057-SN Rev E Sheet 1 of 2

### 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 In.) Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Pins	N	8		
Pitch	e	1.27 BSC		
Overall Height	A	-	-	1.75
Molded Package Thickness	A2	1.25	-	-
Standoff §	A1	0.10	-	0.25
Overall Width	E	6.00 BSC		
Molded Package Width	E1	3.90 BSC		
Overall Length	D	4.90 BSC		
Chamfer (Optional)	h	0.25	-	0.50
Foot Length	L	0.40	-	1.27
Footprint	L1	1.04 REF		
Foot Angle	φ	0°	-	8°
Lead Thickness	c	0.17	-	0.25
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

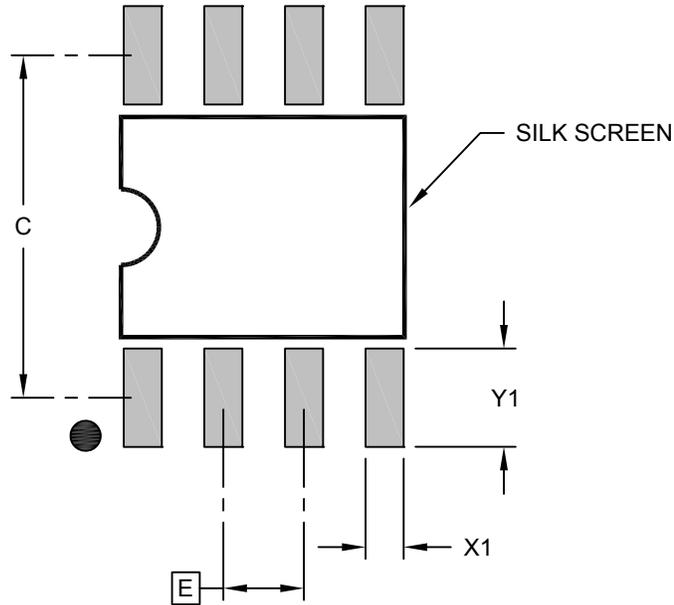
**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.
5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-057-SN Rev E Sheet 2 of 2

**8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



**RECOMMENDED LAND PATTERN**

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	1.27 BSC		
Contact Pad Spacing	C		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

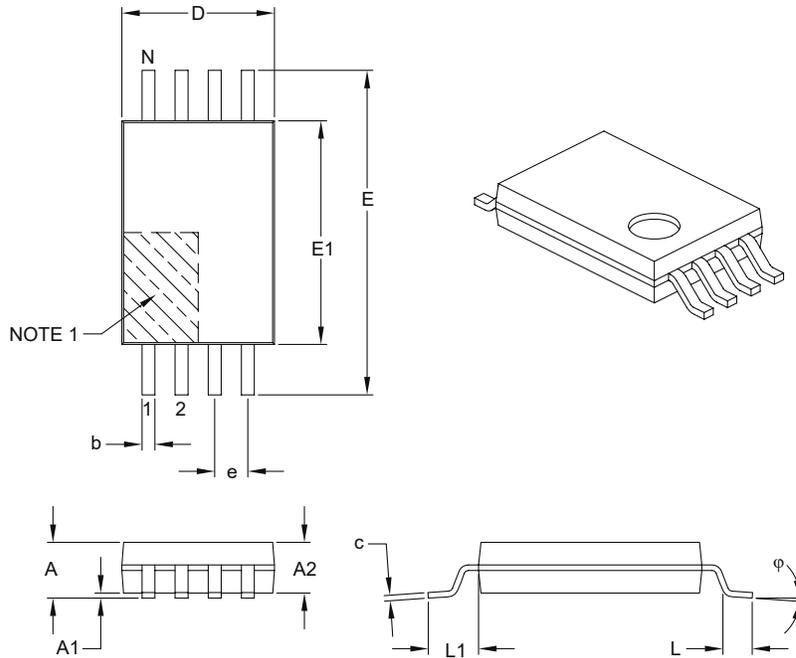
**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M  
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2057-SN Rev E

### 8-Lead Plastic Thin Shrink Small Outline (ST) – 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Pins	N	8		
Pitch	e	0.65 BSC		
Overall Height	A	–	–	1.20
Molded Package Thickness	A2	0.80	1.00	1.05
Standoff	A1	0.05	–	0.15
Overall Width	E	6.40 BSC		
Molded Package Width	E1	4.30	4.40	4.50
Molded Package Length	D	2.90	3.00	3.10
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	$\phi$	0°	–	8°
Lead Thickness	c	0.09	–	0.20
Lead Width	b	0.19	–	0.30

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

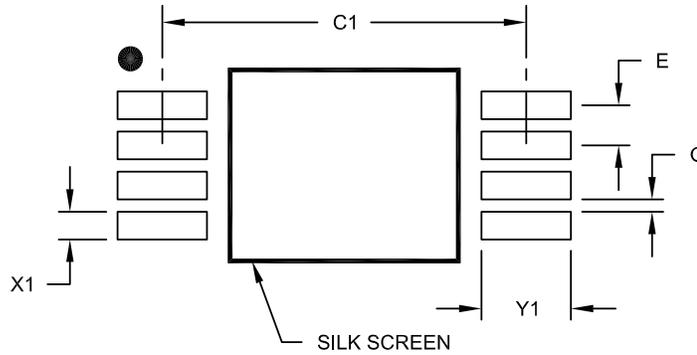
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-086B

### 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



### RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C1		5.90	
Contact Pad Width (X8)	X1			0.45
Contact Pad Length (X8)	Y1			1.45
Distance Between Pads	G	0.20		

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2086A

## **7. Revision History**

### **Revision A (December 2019)**

Updated to the Microchip template. Microchip DS20006276 replaces Atmel document 8674. Updated Package Marking Information. Removed lead finish designation. Updated trace code format in package markings. Updated section content throughout for clarification. Updated the PDIP and SOIC package drawings to Microchip format.

### **Revision C (October 2014)**

Update the 8S1 and the 8A2 to 8X packages, template, Atmel logos, and disclaimer page. No change in functional specification.

### **Revision B (October 2009)**

Updated Lit number and date and removed preliminary status.

### **Revision A (April 2009)**

Initial document release.

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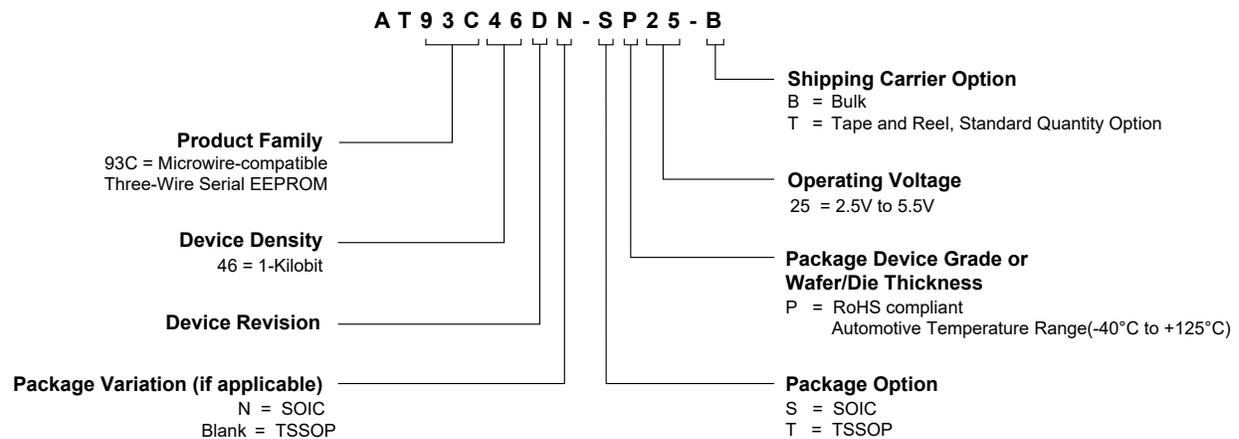
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- Embedded Solutions Engineer (ESE)
- Technical Support

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### Examples

Device	Package	Package Drawing Code	Package Option	Shipping Carrier Option	Device Grade
AT93C46DN-SP25-B	SOIC	SN	S	Bulk (Tubes)	Automotive Temperature (-40°C to 125°C)
AT93C46DN-SP25-T	SOIC	SN	S	Tape and Reel	
AT93C46D-TP25-B	TSSOP	ST	T	Bulk (Tubes)	
AT93C46D-TP25-T	TSSOP	ST	T	Tape and Reel	

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